# 2-JAW PARALLEL GRIPPERS SERIES GEP2000

### PRODUCT ADVANTAGES



### "The electric compact one"

### Largest stroke in small installation space

Do you require a large stroke, due to the fact that you are operating either a form fit gripper or a large range of parts but the installation space and the load capacity of your application is limited? Then this gripper is perfect for you!

### Adjustable gripping force

Using pressures that are too high can damage your workpieces! You can optimally adjust the gripping force to your workpiece by means of the integrated potentiometer or over the control system via IO-Link.

### The simplest activation

It is your choice whether you want to control the gripper by means of I/O ports—like a valve—or if you prefer the version with IO-Link. Both have this in common: they are easy to integrate into your control system.

### SERIES CHARACTERISTICS

Installation size		Variants	
GEP20XX	IL-00	IO-00	IO-05
No-Link	•		
I/O Digital I/O		•	•
10 million maintenance-free cycles (max.)	•	•	•
Hagnetic field sensor		•	
Integrated sensing	•		•
Gripping force adjustable	•	•	•
Self locking mechanism	•	•	•
IP 40 IP40	•	•	•

### BENEFITS IN DETAIL



### TECHNICAL DATA

	Stroke per jaw	Gripping force	Weight	IP class
Installation size	[mm]	[N]	[kg]	
GEP2006	6	40 - 145	0.18	IP40
GEP2010	10	50 - 200	0.31	IP40
GEP2013	13	90 - 360	0.54	IP40
GEP2016	16	125 - 500	0.9	IP40

### FURTHER INFORMATION





### Adjustable gripping force

- Four-level gripping force adjustment via rotary switch for digital gripper control
- For the IO-Link variant, gripping force can be conveniently adjusted using the control system

### **Operating safety**

- Mechanical self-locking mechanism, which means that in the event of a power failure, the workpiece is held securely
- Gripper can be mechanically opened by means of an Allen key

# 2-JAW PARALLEL GRIPPERS INSTALLATION SIZE GEP2013

### PRODUCT SPECIFICATIONS



### Gripping force diagram



### Forces and moments

Displays static forces and moments that can also have an effect, besides the gripping force.



### TECHNICAL DATA

	Technical data		
Order no.	GEP2013IL-00-A	GEP2013IO-00-A	GEP2013IO-05-A
Control	😢 IO-Link	Digital I/O	Digital I/O
Integrated position sensing	Using process data	No	Analog 0 to 10 V
Stroke per jaw [mm]	13	13	13
Gripping force safety device	mechanical	mechanical	mechanical
Control time [s]	0.055	0.055	0.055
Dead weight of mounted gripper finger max. [kg]	0.15	0.15	0.15
Length of the gripper fingers max. [mm]	100	100	100
Repetition accuracy +/- [mm]	0.02	0.02	0.02
Operating temperature [°C]	+5 +60	+5 +60	+5 +60
Voltage [V]	24	24	24
Current consumption max. [A]	2	2	2
Minimum positioning path per jaw [mm]	0.5	0.5	0.5
Protection to IEC 60529	IP40	IP40	IP40
Weight [kg]	0.54	0.54	0.54

### ► TECHNICAL DATA OF THE FORCE LEVELS

	Level 1		
Order no.	GEP2013IL-00-A	GEP2013IO-00-A	GEP2013IO-05-A
Gripping force [N]	90	90	90
Closing time / Opening time [s]	0.42 / 0.42	0.42 / 0.42	0.42 / 0.42
	Level 2		
Order no.	GEP2013IL-00-A	GEP2013IO-00-A	GEP2013IO-05-A
Gripping force [N]	180	180	180
Closing time / Opening time [s]	0.32 / 0.32	0.32 / 0.32	0.32 / 0.32
	Level 3		
Order no.	GEP2013IL-00-A	GEP2013IO-00-A	GEP2013IO-05-A
Gripping force [N]	270	270	270
Closing time / Opening time [s]	0.26 / 0.26	0.26 / 0.26	0.26 / 0.26
	Level 4		
Order no.	GEP2013IL-00-A	GEP2013IO-00-A	GEP2013IO-05-A
Gripping force [N]	360	360	360
Closing time / Opening time [s]	0.23 / 0.23	0.23 / 0.23	0.23 / 0.23

### TECHNICAL DRAWINGS



# **2-JAW PARALLEL GRIPPERS INSTALLATION SIZE GEP2013**

### ACCESORIES



### INCLUDED IN DELIVERY



390677

### YOU CAN FIND CONFIGURATION EXAMPLES ON THE FOLLOWING PAGES



### RECOMMENDED ACCESSORY GEP2013IL-00-A



### **CONNECTIONS / OTHER**





Plug-in connector straight Adapter plate 5 m - plug, socket M12

### RECOMMENDED ACCESSORY GEP2013IO-00-A



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MFS01-S-KHC-P1-PNP Magnetic field sensor angled, cable 0.3 m - M8 connector

MFS02-S-KHC-P1-PNP M Magnetic field sensor straight, 2cable 0.3 m - M8 connector blo

### MFS01-S-KHC-P2-PNP 2-point sensor angled, cable 0.3 m - M8 connector



•••

2-point sensor straight, cable 0.3 m - M8 connector

# CONNECTIONS / OTHER



Plug-in connector Straight Ca-

ble 5m - Socket M8 (female)



ble 5m - Socket M8 (female)



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S8-G-3 Plug-in connector customizable Straight - Connector M8

### **S8-G-4** Plug-in connector customizable Straight - Connector M8



AP2013 Adapter plate

### RECOMMENDED ACCESSORY GEP2013IO-05-A



### **CONNECTIONS / OTHER**



KAG500B5 Plug-in connector Straight Cable 5m - Socket M8 (female)



AP2013 Adapter plate



# 2-JAW PARALLEL GRIPPERS SERIES GEP2000 FUNCTIONAL DESCRIPTION

SENSORS





### 1-point magnetic field sensors - MFS

For non-contact sensing of the piston position

The sensor is clamped in the C-groove of the gripper and detects the magnet attached to the gripper jaws. The MFS02 is available in versions with 5 m cables with exposed leads and 0,3 m cable with connector.



### 2-point magnetic field sensors - MFS

### With two freely programmable switching points

Using the programming unit integrated in the cable, two switch points can be freely defined for this sensor. To do so, the sensor is clamped in the C-groove, the gripper approaches position one and the position is taught in using the teach button. Afterwards, the second position is approached with the gripper and programmed. To ensure use in a wide variety of space conditions, the sensors are available in two variants. While the horizontal MFS02, with straight cable outlet, disappears into the C-groove of the gripper almost completely, the vertical MFS01 is taller, but has a cable outlet that is offset at an angle of 90°. The sensors are available in versions with 5 m cables with exposed leads and 0,3 m cable with connector.

# CONNECTIONS / OTHER



### **Plug-in connectors**

For extending and fabricating the connection lines

Cables with a length of 5 m with exposed leads are available. Depending on the specific needs, the cables can be shortened or fabricated with connectors in sizes M8 and M12. A 5 m long cable with connector / socket is available for the IO-Link connection.



### Adapter plate

Additional screw connection option

By attaching the optional adapter plate, the gripper can also be screwed on vertically (from above) if the fastening options integrated into the gripper housing cannot be used for space reasons.

# 2-JAW PARALLEL GRIPPERS SERIES GEP2000 FUNCTIONAL DESCRIPTION



**CONNECTIONS / OTHER** 



### **Centering sleeves**

For defined position measurement of the gripper fingers

The centering sleeves are inserted into the fits of the gripper jaws to define the position of the gripper fingers. The centering sleeves are comparable to a pin connection.

# CONTROL GEP2000 SERIES





**3** DIGITAL CONTROL + INTEGRATED ANALOG SENSING — GEP2000IO-05



### IO-LINK CONTROL — GEP2000IL-00

- Single-cable solution—control system data, status/sensor data and power supply over a single cable
- Bi-directional data transmission
- Gripping force and gripping speed can be configured using software
- 32 workpieces data sets can be programmed
- Parts detection in range of +/- 0.05 mm with freely teachable area
- Status data such as temperature and cycle number can be read out
- Can be integrated into ZIMMER HMI

### DIGITAL CONTROL — GEP2000IO-00

- Single-cable solution-control system data and power supply over a single cable
- Gripper commissioning by means of digital signals
- Optional digital gripper position feedback via external sensors
- Gripping force adjustment in four levels to the object being gripped, using rotary switch
- Can be integrated into ZIMMER HMI

### 3

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### DIGITAL CONTROL + INTEGRATED ANALOG SENSING — GEP2000IO-05

- Single-cable solution—control system data, sensor data and power supply over a single cable
- Gripper activation by means of digital signals
- Integrated analog feedback of the gripper position
- Gripping force adjustment in four levels to the object being gripped, using rotary switch
- Can be integrated into ZIMMER HMI

# SECURED CONFIGURATION EXAMPLES GEP2000 SERIES

### GEP2000-IL-00 (IO-LINK) WIRING TO CONTROL CABINET (BECKHOFF)



### GEP2000-IL-00 (IO-LINK) WIRING TO CONTROL CABINET (SIEMENS)



### GEP2000-IL-00 (IO-LINK) WIRING TO IO-LINK MASTER IP67 (BECKHOFF)





### ► GEP2000-IO-00 (DIGITAL IO) WIRING TO CONTROL CABINET



### ▶ GEP2000-IO-05 (DIGITAL IO / ANALOG) WIRING TO CONTROL CABINET



# IO-LINK MEETS DIGITAL I/O SMART COMMUNICATION MODULE

### IO-Link meets digital I/O

The Smart Communication Module (SCM) is a master gateway that is suitable for all IO-Link components. With its two channels, the SCM can control two devices and on a functional level, offers the direct implementation of IO-Link to digital I/O. The module thus makes it possible to integrate IO-Link devices into a digital infrastructure and utilize almost the full extended range of functions of the IO-Link device.

# Image: Construction of the construc

### PRODUCT ADVANTAGES

- Translates IO-Link to digital inputs and outputs digital I/O) and from digital I/O to IO-Link
- Easy control of intelligent IO-Link grippers via 24 V digital I/O
- Configuration and training take place using the corresponding intuitive guideZ software
- Can be used with one or two grippers depending on the flexibility required
- Up to 15 different workpieces can be trained for one gripper

### BENEFITS IN DETAIL



	Technical Data
Order no.	SCM-C-00-00-A
Control	Digital I/O
IO logic	PNP
Number of grippers, max.	2
Number of pins (control system input)	12
Number of pins (control system output)	12
Configuration for interface	Ethernet RJ45
Mounting options	35 mm top-hat rail
Voltage [V]	24
Load supply peak current [A]	10
Logic supply peak current [A]	1
Operating temperature [°C]	5 +50
Protection to IEC 60529	IP20
Weight [kg]	0.19

# TOPOLOGY CONNECTION

### Configuration and operation

Up to two Zimmer IO-Link devices can be connected to one Smart Communication Module. The digital inputs and outputs are wired directly to the robot controller or PLC. Simple digital control enables bidirectional communication. To configure the gripper parameters, a temporary network connection is established to a commercially available PC.

As soon as the parameters have been configured intuitively, this connection is no longer necessary. Next, the handling unit is automatically controlled directly via robot controller or PLC.





### 1 Connection

- ► IO-Link gripper
- Digital I/Os on the robot control system/PLC
- Power supply

### 2 Configuration

Temporary network connection via PC for use of the guideZ, expertZ and monitorZ software

### **FURTHER INFORMATION IS AVAILABLE ONLINE**



All information just a click away at: www.zimmer-group.com. Find data, illustrations, 3D models and operating instructions for your installation size using the order number for your desired product. Quick, clear and always up-to-date.